## Solutions to the final exam Questions

**Exercise 1**(20 pt) Consider the map  $F : \mathbb{R}^3 \to \mathbb{R}$  given by  $F(x, y, z) := x^2 + y^2 - z^2$ .

a) For which  $c \in \mathbb{R}$  is  $M_c := F^{-1}(c)$  a smooth submanifold of  $\mathbb{R}^3$ ? Give a sketch of  $M_c$  for all  $c \in \mathbb{R}$ .

Solution: The derivative of F is given by  $d_{(x,y,z)}F = (2x, 2y, -2z) : \mathbb{R}^3 \to \mathbb{R}$  and is surjective for all  $(x, y, z) \neq 0$ . So  $(0, 0, 0) \in F^{-1}(0)$  is the only point where F is not a submersion, showing that  $M_c = F^{-1}(c)$  is a smooth submanifold of  $\mathbb{R}^3$  for all  $c \neq 0$ . (Sketch: see last page of this file)

 $M_0$  is not a smooth submanifold, in fact it is not even a topological manifold! It is given by a cone, and a neighborhood of the tip of the cone can not be homeomorphic to a disc, for it becomes disconnected if you remove the tip itself.

b) Show that  $M_1$  is diffeomorphic to  $S^1 \times \mathbb{R}$  and that  $M_{-1}$  is diffeomorphic to  $\mathbb{R}^2 \coprod \mathbb{R}^2$ .

Solution:  $M_1 = \{(x, y, z) | x^2 + y^2 = 1 + z^2\}$ . Since  $1 + z^2$  is always positive, this is a union of circles as z varies. Explicitly, define  $\varphi : S^1 \times \mathbb{R} \to M_1$  by  $\varphi(a, b, t) := (\sqrt{1 + t^2}a, \sqrt{1 + t^2}b, t)$  where  $t \in \mathbb{R}$  and  $(a, b) \in S^1 \subset \mathbb{R}^2$  (seen as the unit circle). This is a smooth map because it is the restriction of the smooth map from  $\mathbb{R} \times \mathbb{R}^2$  to  $\mathbb{R}^3$  given by the same formula. Define  $\psi : M_{-1} \to S^1 \times \mathbb{R}$  by  $\psi(x, y, z) := (\frac{1}{\sqrt{1 + z^2}}x, \frac{1}{\sqrt{1 + z^2}}y, z)$ . This is again a smooth map and it is inverse to  $\varphi$ .

Next consider  $M_{-1} = \{(x, y, z) \in \mathbb{R}^3 | z^2 = x^2 + y^2 + 1\} = M_{-1}^+ \coprod M_{-1}^-$  where  $M_{-1}^{\pm} := \{(x, y, z) \in \mathbb{R}^3 | z = \pm \sqrt{x^2 + y^2 + 1}\}$ . Both  $M_{-1}^{\pm}$  are the graph of a smooth function on  $\mathbb{R}^2$ , hence are diffeomorphic to  $\mathbb{R}^2$ . (The diffeomorphism itself can be taken to be the projection  $(x, y, z) \mapsto (x, y)$ , with inverse  $(x, y) \mapsto (x, y, \pm \sqrt{x^2 + y^2 + 1})$ .)

## Exercise 2(20 pt)

a) Let V and W be vector spaces and  $L: V \to W$  a linear map. Recall that the rank of L is the dimension of its image  $L(V) \subset W$ . Show that the rank of L is the biggest number k for which  $\Lambda^k L: \Lambda^k V \to \Lambda^k W$  is nonzero. (Hint: construct a convenient basis for V.)

Solution: Let  $v_1, \ldots, v_n$  be a basis for V such that  $\ker(L) = \langle v_{k+1}, \ldots, v_n \rangle$ . The elements  $Lv_1, \ldots, Lv_k$  then form a basis for  $\operatorname{Im}(L)$  and k equals the rank of L. Now a basis for  $\Lambda^l V$  is given by all the products  $v_{i_1} \wedge \ldots \wedge v_{i_l}$  for which  $1 \leq i_1 < \ldots < i_l \leq n$ . Then,

$$\Lambda^{l}(L)(v_{i_{1}} \wedge \ldots \wedge v_{i_{l}}) = Lv_{i_{1}} \wedge \ldots \wedge Lv_{i_{l}}$$

which clearly is zero if l > k, for then necessarily  $i_l > k$ . Moreover,

$$\Lambda^{l}(L)(v_{1} \wedge \ldots \wedge v_{k}) = Lv_{1} \wedge \ldots \wedge Lv_{k}$$

is nonzero because the elements  $Lv_1, \ldots, Lv_k$  are linearly independent.

b) For a nonzero vector  $v \in V$  we consider for each  $k \ge 0$  the linear map  $v \land : \Lambda^k V \to \Lambda^{k+1} V$ given by  $\alpha \mapsto v \land \alpha$ . Show that its kernel is given by the image of  $v \land : \Lambda^{k-1} V \to \Lambda^k V$ . (Hint: construct a convenient basis for V.)

Solution: Since  $v \neq 0$  we can complement it to a basis  $v_1, \ldots, v_n \in V$ , where  $v_1 = v$ . For k = 0 we know that  $v \wedge : \Lambda^0 V = \mathbb{R} \to \Lambda^1 V = V$  is injective, since it maps 1 to  $v \neq 0$ . For k > 0, the elements  $v_1 \wedge v_{i_2} \wedge \ldots \wedge v_{i_k}$  lie in the kernel of  $v_1 \wedge$ , while the elements  $v_{i_1} \wedge v_{i_2} \wedge \ldots \wedge v_{i_k}$  with  $1 < i_1 < \ldots < i_k \leq n$  are mapped by  $v_1 \wedge$  to a basis of  $\operatorname{Im}(v_1 \wedge)$ . Indeed, this follows from the fact that the elements  $v_1 \wedge v_{i_1} \wedge v_{i_2} \wedge \ldots \wedge v_{i_k}$  are all linearly independent in  $\Lambda^{k+1}V$ . So we see that  $\ker(v_1 \wedge) = \langle v_1 \wedge v_{i_2} \wedge \ldots \wedge v_{i_k} | 1 < i_2 < \ldots < i_k \leq n \rangle$ , which is precisely the image of  $v_1 \wedge : \Lambda^{k-1}V \to \Lambda^k V$ . **Exercise 3**(30 pt) Consider the two-form  $\omega = xdy \wedge dz + ydz \wedge dx + zdx \wedge dy$  on  $\mathbb{R}^3$ .

a) Compute  $\int_{S^2(r)} \omega$ , where  $S^2(r) := \{(x, y, z) \in \mathbb{R}^3 | x^2 + y^2 + z^2 = r^2\}$  is the two-sphere of radius r > 0 in  $\mathbb{R}^3$ .

Solution: By Stokes we know that  $\int_{S^2(r)} \omega = \int_{B(r)} dw = 3 \int_{B(r)} dx \wedge dy \wedge dz$ , where  $B(r) = \{(x, y, z) \in \mathbb{R}^3 | x^2 + y^2 + z^2 \leq r^2\}$ . Using polar coordinates this gives

$$\int_{S^2(r)} \omega = 4\pi r^3.$$

b) Let  $\alpha := f \cdot \omega \in \Omega^2(\mathbb{R}^3 \setminus 0)$  where f is the function given by  $f(x, y, z) := (x^2 + y^2 + z^2)^{-\frac{3}{2}}$ . Show that  $d\alpha = 0$  and use this to conclude that  $\int_{S^2(r)} \alpha$  is independent of  $r \in \mathbb{R}_{>0}$ . What is its value?

Solution: We have  $d\alpha = df \wedge \omega + f d\omega$ , and

$$df \wedge \omega = -\frac{3}{2}(x^2 + y^2 + z^2)^{-5/2}(2xdx + 2ydy + 2zdz) \wedge (xdy \wedge dz + ydz \wedge dx + zdx \wedge dy)$$
$$= -3fdx \wedge dy \wedge dz = -fd\omega,$$

which shows that  $d\alpha = 0$ . Now consider the manifold  $A(r_1, r_2) := \{(x, y, z) \in \mathbb{R}^3 | r_1 \le x^2 + y^2 + z^2 \le r_2\}$  for  $0 < r_1 < r_2$ , with boundary given by  $S^2(r_2) \coprod -S^2(r_1)$ . Stokes then gives us

$$0 = \int_{A(r_1, r_2)} d\alpha = \int_{S^2(r_2)} \alpha - \int_{S^2(r_1)} \alpha.$$

This shows that the integral is independent of  $r \in \mathbb{R}_{>0}$ . To see what it is, we take r = 1. There f = 1, hence  $\alpha = \omega$ , and from a) we deduce that  $\int_{S^2(r)} \alpha = 4\pi$ .

c) Let V be the vector field on  $\mathbb{R}^3 \setminus 0$  given by  $V_{(x,y,z)} := x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z}$ . Compute the flow  $\varphi_t^V$  of V and show that  $(\varphi_t^V)^* \alpha = \alpha$ . Use this to give another proof of the fact that  $\int_{S^2(r)} \alpha$  is independent of r.

Solution: The flow of V is given by  $\varphi_t^V(x, y, z) := e^t(x, y, z)$ . Indeed,  $\varphi_0^V = \text{Id}$ , and

$$\frac{d}{dt}\varphi_t^V(x,y,z) = e^t(x,y,z) = V_{e^t(x,y,z)} = V_{\varphi_t^V(x,y,z)}$$

To show that  $(\varphi_t^V)^* \alpha = \alpha$  we can do two things. We can check it directly:

$$(\varphi^V_t)^*\alpha = (\varphi^V_t)^*f \cdot (\varphi^V_t)^*\omega = e^{-3t}f \cdot e^{3t}\omega = f\omega = \alpha$$

or we can compute the Lie derivative:

$$\mathcal{L}_V \alpha = \iota_V d\alpha + d\iota_V \alpha = 0,$$

because  $d\alpha = 0$  and  $\iota_V \alpha = f \iota_V \omega$  and  $\iota_V \omega = 0$  as one readily verifies. Since  $\varphi_t^V$  gives orientation preserving diffeomorphisms from  $S^2(r)$  to  $S^2(e^t r)$ , we see that  $\int_{S^2(e^t r)} \alpha = \int_{S^2(r)} (\varphi_t^V)^* \alpha = \int_{S^2(r)} \alpha$ . (The fact that  $\varphi_t^V$  is orientation preserving follows from its explicit formula, but it is true for every flow in general because it can be continuously deformed to the identity map.)

**Exercise** 4(30 pt) For this exercise you may use without proof that  $\int_{S^n} : H^n(S^n) \to \mathbb{R}$  is an isomorphism. Let  $\pi : S^n \to \mathbb{RP}^n$  denote the quotient map and  $\iota : \mathbb{R}^{n+1} \to \mathbb{R}^{n+1}$  the antipodal map  $x \mapsto -x$ .

a) Show that a form  $\omega \in \Omega^k(S^n)$  is of the form  $\omega = \pi^* \alpha$  for a unique  $\alpha \in \Omega^k(\mathbb{RP}^n)$  if and only if  $\iota^* \omega = \omega$ . Deduce that  $\frac{1}{2}(\omega + \iota^* \omega) \in \pi^*(\Omega^k(\mathbb{RP}^n))$  for every  $\omega \in \Omega^k(S^n)$ .

Solution: Since  $\pi \iota = \pi$  it follows that  $\iota^* \pi^* = \pi^*$ . In particular,  $\iota^*(\pi^*\alpha) = \pi^*\alpha$  for all  $\alpha \in \Omega^k(\mathbb{RP}^n)$ . Conversely, suppose that  $\iota^*\omega = \omega$  for  $\omega \in \Omega^k(S^n)$ . The map  $\pi : S^n \to \mathbb{RP}^n$  is a local diffeomorphism, and the inverse image of a point  $[x] \in \mathbb{RP}^n$  consists of two points;  $\pm x \in S^n$ . Hence, there are neighborhoods V of [x] in  $\mathbb{RP}^n$  and  $U_{\pm}$  of  $\pm x$  in  $S^n$  such that  $\pi|_{U_{\pm}} : U_{\pm} \to V$  is a diffeomorphism. So, there are unique  $\alpha_{\pm} \in \Omega^k(V)$  with the property that  $(\pi|_{U_{\pm}})^*\alpha_{\pm} = \omega|_{U_{\pm}}$ . Observe that  $\pi|_{U_{\pm}} = \pi|_{U_{-}} \circ \iota$ , hence  $(\pi|_{U_{+}})^*\alpha_{-} = \iota^*(\pi|_{U_{-}})^*\alpha_{-} = \iota^*\omega|_{U_{-}} = \omega|_{U_{+}} = (\pi|_{U_{+}})^*\alpha_{+}$ . In particular,  $\alpha_{+} = \alpha_{-}$ . We have now shown that around each point in  $\mathbb{RP}^n$  there is a unique  $\alpha$  with the desired property. By uniqueness all these locally constructed  $\alpha$ 's glue together into a globally defined  $\alpha \in \Omega^k(\mathbb{RP}^n)$ . The last question follows immediately since  $\iota^*(\frac{1}{2}(\omega + \iota^*\omega)) = \frac{1}{2}(\iota^*\omega + \omega)$ , because  $\iota \circ \iota = \mathrm{Id}$ .

b) If n is even and  $\iota^* \omega = \omega$ , show that  $\int_{S^n} \omega = 0$ .

Solution: Let  $D^+, D^- \subset S^n$  be the upper and lower hemisphere. Then  $\iota$  induces a diffeomorphism  $\iota : D^+ \to D^-$ , which for n even is orientation reversing. Indeed, for n even the map  $\iota : \mathbb{R}^{n+1} \to \mathbb{R}^{n+1}$  is orientation reversing, and maps an outward normal of  $S^n$  to another outward normal of  $S^n$ . Hence the restriction  $\iota_{S^n} : S^n \to S^n$  is orientation reversing. Consequently:

$$\int_{S^n} \omega = \int_{D^+} \omega + \int_{D^-} \omega - = \int_{D^+} \omega + \int_{D^-} \iota^* \omega = \int_{D^+} \omega - \int_{D^+} \omega = 0$$

c) Show that  $H^n(\mathbb{RP}^n) = 0$  for all even n. Deduce that  $\mathbb{RP}^n$  is not orientable for n even. (Hint: for  $\omega \in \Omega^n(\mathbb{RP}^n)$  show that  $\pi^*\omega$  is exact. Then use part a) to write  $\pi^*\omega = d\alpha$  for some  $\alpha$  with  $\iota^*\alpha = \alpha$ .)

Solution: Let  $\omega \in \Omega^n(\mathbb{RP}^n)$ . By a) and b) we know that  $\int_{S^n} \pi^* \omega = 0$ , so by the given fact about  $H^n(S^n)$  we know that  $\pi^* \omega = d\alpha$  for some  $\alpha \in \Omega^{n-1}(S^n)$ . This  $\alpha$  need not satisfy  $\iota^* \alpha = \alpha$ , but we can consider  $\widetilde{\alpha} := \frac{1}{2}(\alpha + \iota^* \alpha)$ . We have  $\iota^* \widetilde{\alpha} = \widetilde{\alpha}$ , while  $d\widetilde{\alpha} = \frac{1}{2}(d\alpha + \iota^* d\alpha) = \pi^* \omega$ . By part a) again we can write  $\widetilde{\alpha} = \pi^* \beta$  for some  $\beta \in \Omega^{n-1}(\mathbb{RP}^n)$ , and we have  $\pi^* \omega = \pi^* d\beta$ . Using a) once more, this implies  $\omega = d\beta$ , hence  $\omega$  is exact. As  $\omega$  was arbitrary,  $H^n(\mathbb{RP}^n) = 0$ .

**Exercise 5**(20 pt) Recall that a vector bundle  $\pi : E \to M$  is called orientable if we can choose an orientation on each fiber, in such a way that around each point in M we can find a positively oriented frame.

- a) Show that a line bundle (i.e. a vector bundle of rank 1) is trivial if and only if it is orientable. Solution: Clearly if E is trivial, i.e. isomorphic to  $M \times \mathbb{R}$ , it is orientable since we can pick a nowhere vanishing section and let that induce an orientation on each fiber. Conversely, suppose that E is orientable. Choose an open cover  $\{U_{\alpha}\}$  of M together with positively oriented sections  $s_{\alpha} \in \Gamma(E|_{U_{\alpha}})$ . Let  $\{\rho_{\alpha}\}$  be a partition of unity subordinate to  $\{U_{\alpha}\}$ . Then  $\rho_{\alpha}s_{\alpha} \in \Gamma(E)$ , i.e. is a globally defined section of E. Let  $s := \sum_{\alpha} \rho_{\alpha}s_{\alpha} \in \Gamma(E)$  (this is welldefined since the sum is locally finite). If  $x \in M$ ,  $s(x) = \sum_{\alpha} \rho_{\alpha}(x)s_{\alpha}(x)$ , and all the  $s_{\alpha}(x)$ are nonnegative in  $E_x$  with respect to the given orientation. Moreover, whenever  $\rho_{\alpha}(x) > 0$ ,  $s_{\alpha}(x) > 0$ , and we know that there is at least one  $\alpha$  for which this is true since  $\sum_{\alpha} \rho_{\alpha} = 1$ .
- b) Show that for any line bundle E over M the line bundle  $E \otimes E$  is trivial. (Hint: use a))

Solution: We will construct an orientation on  $E \otimes E$ . This is based on the following observation: if  $v \in E_x$  is nonzero, it defines a nonzero element  $v \otimes v \in E_x \otimes E_x$ , hence an orientation on  $E_x \otimes E_x$ . Moreover, if  $w = \lambda v$  is another nonzero element of  $E_x$ , then  $w \otimes w = \lambda^2 v \otimes v$ . Since  $\lambda^2 > 0$  for every  $\lambda \neq 0$ , we see that this orientation on  $E_x \otimes E_x$  is independent of the choice of nonzero vector in  $E_x$ . We endow all the fibers  $E_x \otimes E_x$  of  $E \otimes E$  with this orientation. This is an orientation of E, i.e. is continuous, because if e is a local frame for E, then  $e \otimes e$  is a frame for  $E \otimes E$  which is positive. Hence,  $E \otimes E$  is oriented and so trivial by part a).



